













Najeebullah, S., Kasi, A., Kasi, J., K., (2018), Design, Development and Control of Long Range Quadcopter, Techno-Science Burdur Mehmet Akif Ersoy University (Turkey), Vol. 1, No.1, p.17-21.

Özen F., (2017). Afetlerde Robotların Kullanımı. Elektrik Mühendisleri Odası İstanbul Şubesi Bülteni (65), 16-21. (Kontrol No: 3634964).

Tee, Y., H., (2013), Development of Autonomous Amphibious Vehicle Maneuvering System Using Wheelbased Guided Propulsion Approach, MSc Thesis, Faculty of Engineering and Science Universiti Tunku Abdul Rahman.

Tee, Y., H., Tan, Y., Teoh, B., Y., Tan, E., B., Wong, Z., Y., (2010), A Compact Design of Zero-Radius Steering Autonomous Amphibious Vehicle with Direct Differential Directional Drive - UTAR-AAV", 2010 IEEE Conference on Robotics, Automation and Mechatronics, pp. 176-181, DOI: 10.1109/RAMECH.2010.5513192.